

# III. Timed Automata.

Notiztitel

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## III.1. Syntax

Kripke-Structure:

States

Locations

L

Timed automaton:

Start states

Start locations

$L_0$

Labelling function

✓

I

Transition relation.

✓

$\rightarrow$

Clocks

C

└ constraints

CC

└ resets.

TA:  $(L, L_0, I, \rightarrow, C, i_{tr}, r)$

$I: L \rightarrow 2^{AP}$

$\rightarrow \in L \times L$

$r: (\rightarrow) \rightarrow 2^C$

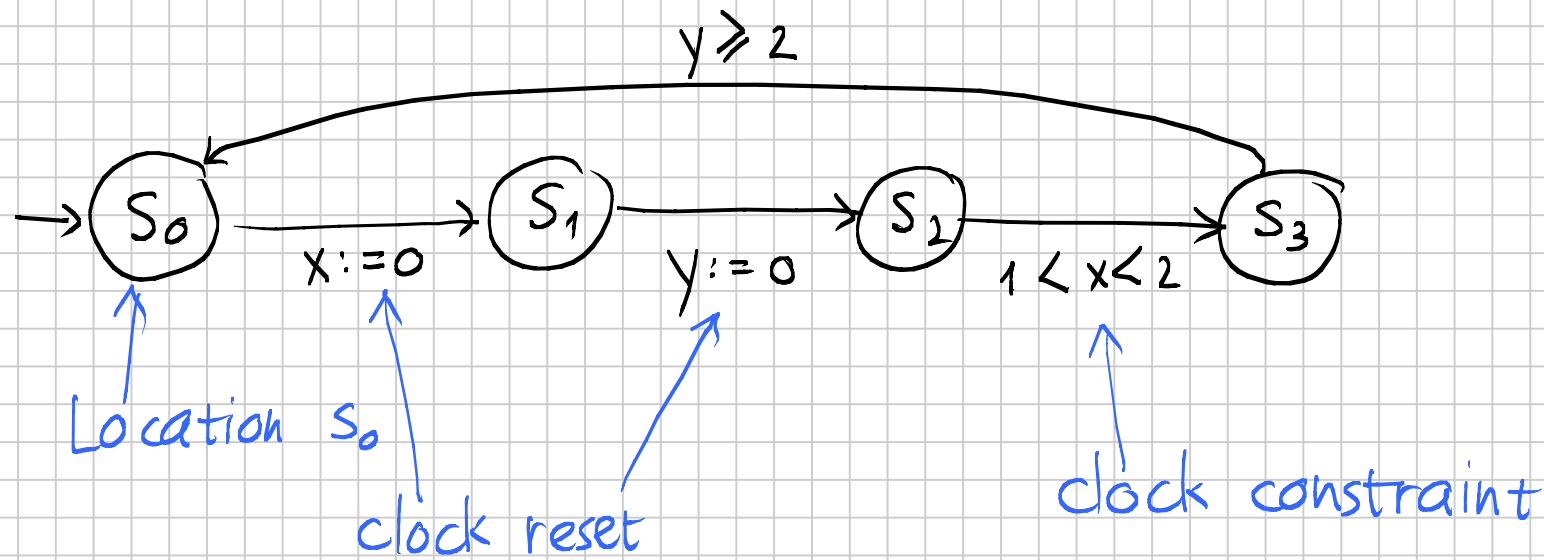
$i_{tr}: (\rightarrow) \rightarrow CC$

- Clock:
1. Start with all clocks = 0
  2. Clocks run with the time
  3. Transition  $t \in \rightarrow$  is only enabled if  $i_{tr}(t)$  is true.  
If  $t$  is taken,  $r(t)$  are reset.

Clock constraints: conjunctions of conditions like

$$x \geq c, x > c, x \leq c, x < c \quad \begin{array}{l} (c \in \mathbb{N}) \\ (x \in C) \end{array}$$

Clock reset: a set of clocks, with the interpretation: reset these clocks to 0.



### III.2 Semantics of Timed Automata

Clock assignments: functions  $C \rightarrow \mathbb{R}_0^+$   
 $\mu, \nu, \dots$

States: pairs (Location, Clock assignment)

State changes:  $\begin{cases} \text{time passes} & \text{b)} \\ \text{a transition is taken} & \text{a)} \end{cases}$

Initial state: (Initial location, all clocks are = 0)

$$a) (l, v) \xrightarrow{\text{discrete}} (l', v') \quad \text{if } t = (l, l') \in \rightarrow$$

$i_{tr}(t)$  is satisfied by  $v$

$$v'(x) = \begin{cases} 0 & \text{if } x \in r(t) \\ v(x) & \text{otherwise} \end{cases}$$

$$b) (l, v) \xrightarrow{\text{time}(\delta)} (l', v') \quad \text{if } l' = l$$
$$v'(x) = v(x) + \delta$$

Runs:  $\underbrace{(l_0, v_0)}_{\text{initial state}} \longrightarrow (l_1, v_1) \longrightarrow (l_2, v_2) \longrightarrow \dots$

where each arrow is a discrete or a time transition.

"Wrong" runs:

- only discrete steps : time stops

-  $(l_0, v_0) \xrightarrow{t(\frac{1}{8})} (l_1, v_1) \xrightarrow{t(\frac{1}{4})} (l_2, v_2) \xrightarrow{t(\frac{1}{2})} (l_3, v_3)$   
 $\xrightarrow{t(\frac{1}{8})} \dots$  : convergent time

Zenoness := time does not diverge.

In most semantics, only non-Zeno runs count.

III.3. TCTL : a logic for timed automata.

A) Syntax

Syntax of CTL:  $\phi ::= a \mid \neg \phi \mid \phi \wedge \phi \mid A \varphi \mid E \varphi$

$\varphi ::= X \phi \mid \phi \mathcal{U} \phi$

Syntax of TCTL:  $\phi ::= \text{same}$

$\varphi ::= \phi \mathcal{U}_{\sim c} \phi$   $\sim \in \{<, \leq, >, \geq\}$   
 $c \in \mathbb{N}$

e.g.  $E(\text{red } \mathcal{U}_{\leq 4} \text{ blue})$  it is possible to reach a blue state within 4 time units, only touching a re

## B Semantics

Given a TA  $\mathcal{M} = (L, L_0, I, \rightarrow, C, i_{tr}, r)$ , a state  $(l, v)$  satisfies  $\phi$  if:

$(\mathcal{M}, l, v) \models a$  if  $I(l) \ni a$

$\left. \begin{array}{l} \models \neg \phi \\ \models \phi \wedge \psi \end{array} \right\}$  same as in CTL

$\models A \psi$  if all runs starting in  $(l, v)$  satisfy  $\psi$

$\models E \psi$  if some run etc.

stays

$(\mathcal{M}, (l_0, v_0) \rightarrow (l_1, v_1) \rightarrow \dots) \models \phi \mathcal{U}_{\sim c} \psi$  if there is an  $i$  such that  $(\mathcal{M}, l_i, v_i) \models \psi$ ; for every  $j < i$ , we have  $(\mathcal{M}, l_j, v_j) \models \phi$ , and  $\text{time}(i) \sim c$

A position in a run is a pair  $(i, \delta)$  where

$$i \in \mathbb{N}, \text{ and } \delta = 0 \text{ if } (l_i, v_i) \xrightarrow{\text{discrete}}$$

$$\delta \leq \varepsilon \text{ if } (l_i, v_i) \xrightarrow{\text{time}(\varepsilon)}$$

sometimes  $<$

$$(\mathcal{M}, (l_0, v_0) \rightarrow (l_1, v_1) \rightarrow \dots) \models \phi \text{ or } \psi \text{ if}$$

1. there is a position  $(i, \delta)$  such that

$$(\mathcal{M}, l_i, v_i + \delta) \models \psi$$

2. for every position  $(j, \varepsilon) < (i, \delta)$ , we have

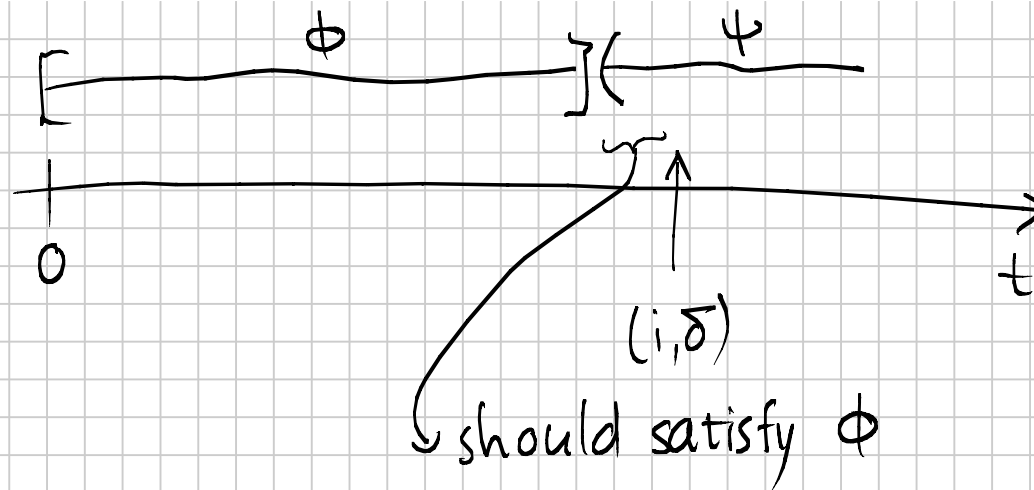
$$(\mathcal{M}, l_j, v_j + \varepsilon) \models \phi$$

3.  $\underbrace{\text{time}(i, \delta)} \sim c$

$$\delta + \sum_{j=0}^{i-1} \delta_j$$

$$\text{where } (l_j, v_j) \xrightarrow{\text{time}(\delta_j)} (l_{j+1}, v_{j+1})$$

Still  
a  
problem.



We accept, for now, that this situation is not handled intuitively,

### III. 4. TCTL Model Checking.

Problem: infinitely many states

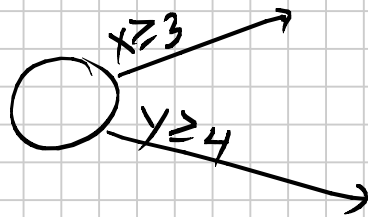
Solution: identify some states via an equivalence relation that respects TCTL-equivalence, similar to yesterday's bisimulations.



States can be distinguished by a suitable TCTL formula if:

- clock assignments like  $x=3,1$  /  $x=4,2$  with different integer values (a formula like  $E \Diamond_{\leq 4} a$ )
- fractional value  $=0$  /  $\neq 0$  ( $E \Diamond_{\leq 4} a$  vs.  $E \Diamond_{< 4} a$ )
- different orderings of fractional values.

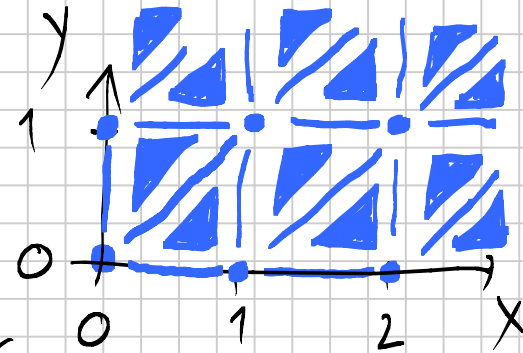
$$\begin{array}{ccc} x=2,1 & ; & y=3,7 & / & x=2,5 & ; & y=3,3 \\ 0,1 & < & 0,7 & & 0,5 & > & 0,3 \end{array}$$



If two clock assignments cannot be distinguished by the above clauses, they are equivalent.

Equivalence classes are called regions.

Example:  $C = \{x, y\}$



no longer  $\mathbb{R}_0^+ \times \mathbb{R}_0^+$  cases,  
but "only" countably many.

We extend this relation to states:  $(l, v) \sim (l', v')$   
if  $l = l'$  and  $v \sim v'$ .

The region automaton:

- states are regions of the original TA.

- transitions are  $\xrightarrow{\text{discrete}}$   $\cup$   $\xrightarrow{\text{time}(\delta)}$   
for small  $\delta$

- Initial states: regions of the original states.

- Labeling: as a single region only contains one location, it is uniquely defined.

→ This is a Kripke structure, no TA any more.

↳ We almost know how to check TCTL formulas now.



Tool : UPPAAL

Uppsala + Aalborg  
Sweden      Denmark

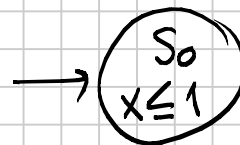
Sweden      Denmark

extends TA by:

- Location invariants.

a function  $i_{loc}: L \rightarrow CC$

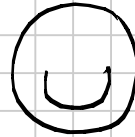
it is not allowed to stay in  $l$   
so long that  $i_{loc}(l)$  would become  
false.



New problem:  
timelock.

Further

UPPAAL extensions: - urgent locations: it is forbidden to wait.



- UPPAAL models may contain multiple TA with synchronisation.

+ add action labels

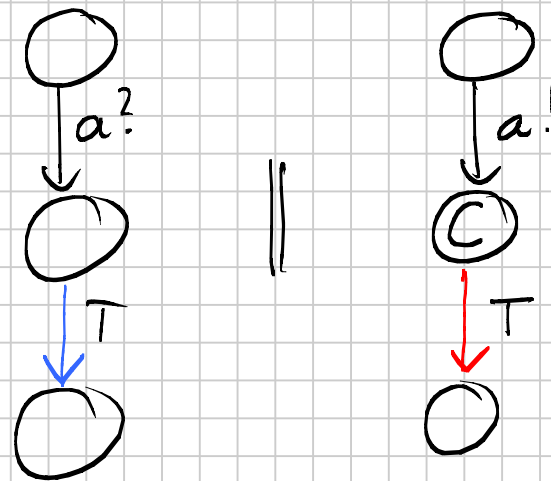
$\longrightarrow \in L \times A \times L$



synchronisation only between  $\langle \text{name} \rangle!$  and  $\langle \text{name} \rangle?$ , exactly two parties.

$$\frac{E \xrightarrow{a!} E' \quad F \xrightarrow{a?} F'}{E \parallel F \xrightarrow{T} E' \parallel F'}$$

- Committed locations: more strict than urgent locations. Must be left in the next transition — no interleaving allowed.



The red arrow must precede the blue arrow.

Uppaal is available at [www.uppaaal.com](http://www.uppaaal.com).

Nachtrag: Checking  $\Phi \mathcal{U} \sim_c \Psi$ .

Main idea: add one more clock, called "formula clock".  $fc$ .

Augmented clock assignments:  $C \cup \{fc\} \rightarrow \mathbb{R}_0^+$ .

Augmented region: same as a region, but with an augmented clock assignment.

In the <sup>augmented</sup> region automaton, add one extra atomic proposition:  $a_{\sim c}$  holds in all states that satisfy:  
 $fc \sim c$ .

Check for  $\Phi \mathcal{U} (\Psi \wedge a_{\sim c})$  in each state of the <sup>augmented</sup> region automaton where  $fc = 0$ .



Finally, map back from the augmented region automaton to the region automaton.

$$(RA, (l, [v])) \models \phi \mathcal{U}_{rc} \psi$$

$$\text{iff } (\text{augm. RA}, (l, [v] \oplus f_c \mapsto 0)) \models \phi \mathcal{U} (\psi \wedge a_{rc})$$

We need a fairness condition to avoid Zeno runs.

A run in the region automaton can correspond to a non-Zeno run in the TA, if for all  $x \in C$

- either the clock  $x$  is reset infinitely often;
- or the clock value of  $x$  is unbounded.

and the run contains infinitely many time steps.